

Comments and Corrections

Erratum

In error, financial support was omitted from the first footnote of [1]. The work was supported in part by the DARPA/SPAWAR Contract N66001-00-C-8026 and Contract N66001-03-C-8045.

REFERENCES

- [1] P.-C. Lin, H. Komsuoğlu, and D. E. Koditschek, "A Leg Configuration Measurement System for Full-Body Pose Estimates in a Hexapod Robot," *IEEE Trans. Robot.*, vol. 21, no. 3, pp. 411–422, Jun. 2005.

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